

**Seventh Semester B.E. Degree Examination, Dec.09/Jan.10**  
**Control Engineering**

Time: 3 hrs

Max. Marks:100

**Note: Answer any FIVE full questions, selecting at least TWO questions from each part.**

**PART -- A**

1.
  - a. Explain open loop and closed loop control systems, with block diagrams. What are the advantages and disadvantages of a closed loop system over an open loop system? (10 Marks)
  - b. What are the requirements of a control system? Briefly explain. (05 Marks)
  - c. Draw the block diagram of proportional integral controller and explain. (05 Marks)
2.
  - a. Obtain the differential equations for the mechanical system shown in Fig.2(a). (10 Marks)

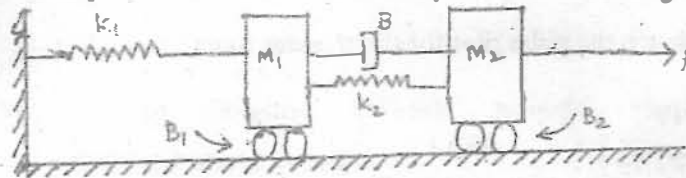


Fig.2(a)

- b. A thermometer is dipped in a vessel containing liquid at a constant temperature of  $\theta_1(t)$ . The thermometer has a thermal capacitance for storing heat as  $C$  and thermal resistance to limit heat flow as  $R$ . If the temperature indicated by the thermometer is  $\theta_2(t)$ , obtain the transfer function of the system. (10 Marks)
3.
  - a. Reduce the block diagram shown in Fig.3(a) to its simplest possible form and find its closed loop transfer function. (10 Marks)

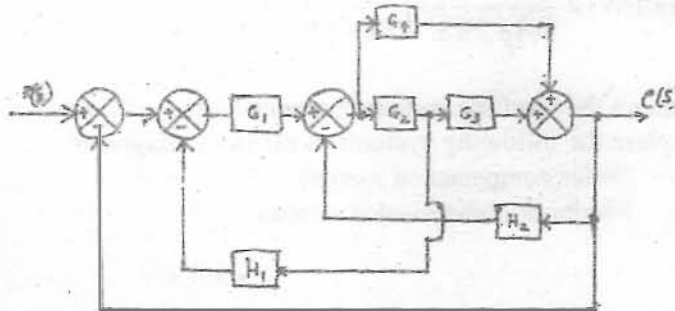


Fig.3(a)

- b. For the system shown in Fig 3(b) determine  $\frac{C(s)}{R(s)}$  using Mason's gain formula. (10 Marks)

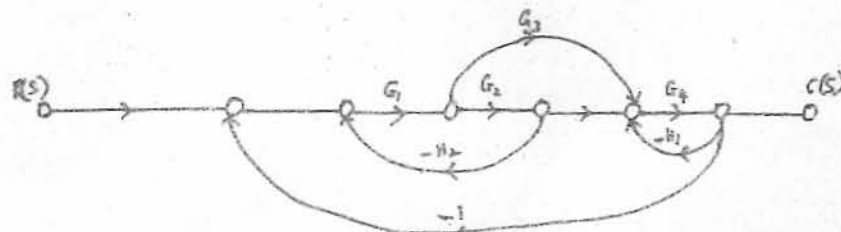


Fig.3(b).

- 4 a. A unity feedback system is characterized by an open loop transfer function

$$G(S) = \frac{10}{S^2 + 5S + 6}$$

Determine the following, when the system is subjected to a unit step input.

- i) Undamped natural frequency
  - ii) Damping ratio
  - iii) Peak overshoot
  - iv) Peak time
  - v) Setting time. (12 Marks)
- b. Ascertain the stability of the system given by the characteristic equation,  
 $S^6 + 3S^5 + 5S^4 + 9S^3 + 8S^2 + 6S + 4 = 0$ , by Routh Hurwitz criterion. (08 Marks)

### PART - B

- 5 a. Sketch the polar plot for the transfer function  $G(S) = \frac{10}{S(S+1)(S+2)}$ . (08 Marks)

- b. Apply Nyquist stability criterion to the system with transfer function  
 $G(s)H(s) = \frac{4S+1}{S^2(1+S)(1+2S)}$  and ascertain its stability. (12 Marks)

- 6 Sketch the Bode plot for  $G(s)H(s) = \frac{2}{S(S+1)(1+0.2S)}$ . Also obtain gain margin and phase margin and crossover frequencies. (20 Marks)

- 7 Sketch the root locus plot for the system, whose open loop transfer function is given by  
 $G(s)H(s) = \frac{K}{S(S+2)(S^2+8S+20)}$ . (20 Marks)

- 8 a. Explain the need for system compensation. List the types of compensators used. (10 Marks)  
 b. Explain the following systems, with block diagrams.  
 i) Series compensated system  
 ii) Feedback compensated system. (10 Marks)

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