

Fourth Semester B.E. Degree Examination, June/July 2013
Control Systems

Time: 3 hrs.

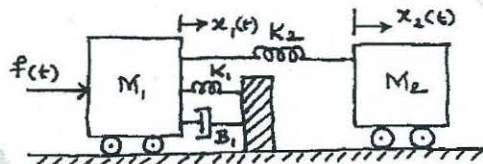
Max. Marks:100

Note: Answer FIVE full questions, selecting at least TWO questions from each part.

PART – A

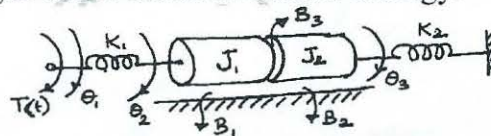
- 1 a. Compare open loop and closed loop control systems and give one practical example of each. (06 Marks)
- b. For the system shown in Fig.Q.1(b) write mechanical network and obtain its mathematical model. (06 Marks)

Fig.Q.1(b)



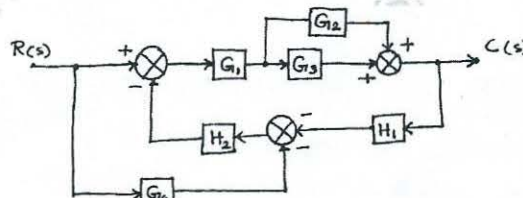
- c. For the system shown in Fig.Q.1(c) write its mechanical network and obtain mathematical model and electrical analogue based on force-current analogy. (08 Marks)

Fig.Q.1(c)



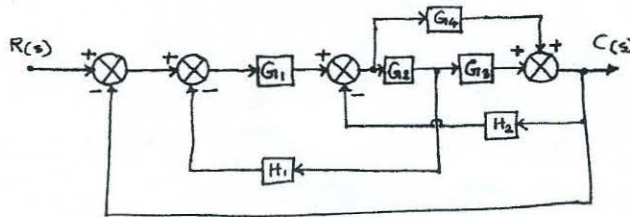
- 2 a. Define transfer function and what are its properties. (05 Marks)
- b. Obtain the transfer function for the block diagram shown in Fig.Q.2(b) using block diagram reduction method. (07 Marks)

Fig.Q.2(b)



- c. For the block diagram, given in Fig.Q.2(c) obtain over all transfer function using Mason's gain formula. (08 Marks)

Fig.Q.2(c)



In completing your answers, compulsorily draw diagonal cross lines on the remaining blank pages. Any revealing of identification, appeal to evaluator and/or equations written eg, 42+8 = 50, will be treated as malpractice.

- a. Draw the time response curve and define time domain specifications for second order S.S. for unit step input. (06 Marks)
- b. A unity feedback control system is given by an open-loop transfer function... (06 Marks)

- c. The open loop transfer function of a servo system with unity feedback is given by

$$G(s) = \frac{10}{s(0.1s+1)}$$

Find out static error constants and obtain steady state error when subjected to an i/p of

$$r(t) = A_0 + A_1 t + \frac{A_2}{2} t^2$$

(08 Marks)

- 4 a. Explain RH stability criterion used for finding of stability of control systems. (06 Marks)
 b. Find the range of K for the system to be stable using RH criterion. (06 Marks)

$$G(s)H(s) = \frac{k(1-s)}{s(s^2+5s+9)}$$

(06 Marks)

- c. Investigate the stability of the system give by characteristic equation
 $S^6 + 2S^5 + 8S^4 + 12S^3 + 20S^2 + 16S + 16 = 0$.

(08 Marks)

PART - B

- 5 a. A feedback control system has an open loop transfer function

$$G(s)H(s) = \frac{K}{s(s+3)(s^2+2s+2)}$$

Draw the root locus as K varies from 0 - to -∞.

(20 Marks)

- 6 a. Define the following terms:

- Resonant peak
- Resonant frequency
- Band width
- Cut off frequency.

(04 Marks)

- b. Sketch the bode plot for the transfer function

$$\frac{300(s^2+2s+4)}{s(s+10)(s+20)}$$

(13 Marks)

- c. Write a note about gain margin in brief.

(03 Marks)

- 7 a. Plot the polar plot for the transfer function given $G(s) = \frac{1}{s(Ts+1)}$.

(06 Marks)

- b. State Nyquist stability criterion.

(02 Marks)

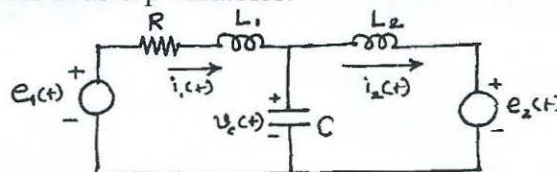
- c. Using Nyquist stability criterion verify stability of the system described below:

$$G(s)H(s) = \frac{5}{s(1-s)}$$

(12 Marks)

- 8 a. Obtain the state model for the electrical system given in Fig.Q.8(a). Take $e_1(t)$, $e_2(t)$ as i/p variables and voltage across R as o/p variables. (08 Marks)

Fig.Q.8(a)



- b. List out the properties of STM.

(05 Marks)

- c. Obtain the state transition matrix for a system matrix given by $A = \begin{bmatrix} 0 & 1 \\ -2 & -3 \end{bmatrix}$.

(07 Marks)
